



# A projection method for the eigenvalues of a delay-differential equation

8th GAMM Workshop - Applied and numerical linear algebra  
Hamburg, 11-12th September, 2008

Hot shower problem

Lambert  $W$

Solution operator

Infinitesimal generator

A Projection method

Numerical examples

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# Delay-differential equations (DDEs)

A projection method  
for the eigenvalues  
of

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Retarded DDE with a single delay

$$\Sigma = \begin{cases} \dot{x}(t) = A_0 x(t) + A_1 x(t - \tau), & t \geq 0 \\ x(t) = \varphi(t), & t \in [-\tau, 0] \end{cases} \quad (1)$$

where  $A_0, A_1 \in \mathbb{R}^{n \times n}$  and  $\varphi : [-\tau, 0] \rightarrow \mathbb{R}^n$ .

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Ansatz:  $x(t) = ve^{st} \Rightarrow$

$$(-sI + A_0 + A_1 e^{-s\tau}) v = 0$$

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## Definition

Spectrum:  $\sigma(\Sigma) := \{s \in \mathbb{C} : \det(-sI + A_0 + A_1 e^{-s\tau}) = 0\}$

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## The hot-shower example

- $x(t)$  = Temp diff from optimal Temp

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- $\alpha$  = Human sensitivity



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## The hot-shower example

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- $\tau = \frac{\text{Length of pipe}}{\text{Speed of water}}$



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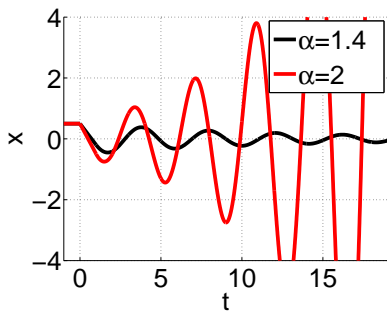
Delayed negative feedback:  $\dot{x}(t) = -\alpha x(t - \tau)$



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Solution  $x(t)$

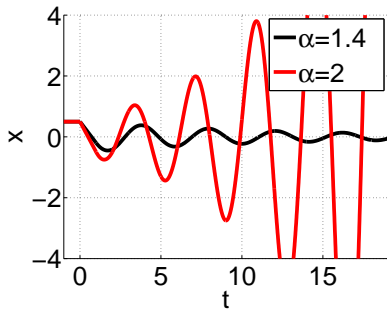




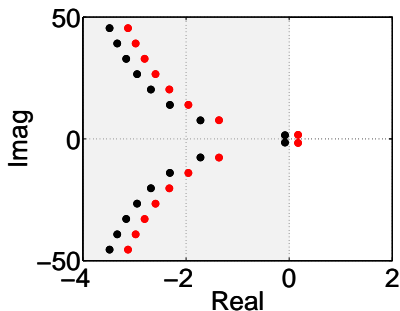
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Solution  $x(t)$



Spectrum

$$\sigma(\Sigma) = \{s \in \mathbb{C} : -s - \alpha e^{-\tau s} = 0\}$$

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# Computing the spectrum

Example ([Ebenbauer, Allgöwer '06])

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# Computing the spectrum

**Example ([Ebenbauer, Allgöwer '06])**

Spectrum  $\sigma(\Sigma)$ :  $s \in \mathbb{C}$  such that

$$\det \left( -sI + \begin{pmatrix} -1 & 13.5 & -1 \\ -3 & -1 & -2 \\ -2 & -1 & -4 \end{pmatrix} + \begin{pmatrix} -5.9 & 7.1 & -70.3 \\ 2 & -1 & 5 \\ 2 & 0 & 6 \end{pmatrix} e^{-\tau s} \right) = 0$$

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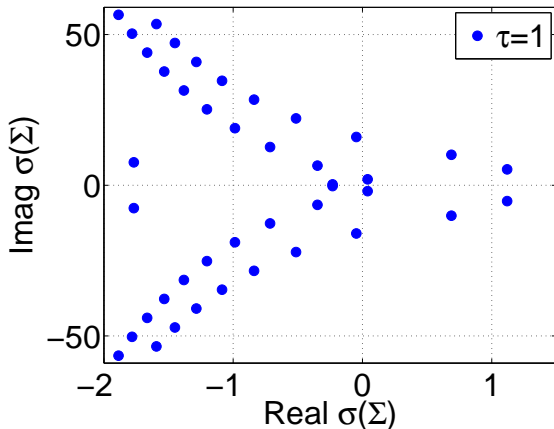
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Methods for  $\sigma(\Sigma) := \{s \in \mathbb{C} : \det(-sI + A_0 + A_1 e^{-s\tau}) = 0\}$

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## Method 1: Lambert W

Analytic method for scalar and simultaneously triangularizable systems.

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## Method 2: Solution operator

Numerical method based on the discretization of the solution operator.

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### Method 4: Subspace accelerated residual inverse iteration

A projection method based on residual inverse iteration.

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- Two examples indicate that Method 4 should be used for large problems.
- Previously in the literature  $n = 131$ , Method 4:  $n = 10^6$ .

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# Method 1: The Lambert W function

Scalar single delay:

$$-s + a_0 + a_1 e^{-s\tau} = 0$$

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Scalar single delay:

$$-s + a_0 + a_1 e^{-s\tau} = 0$$

Multiply with  $\tau e^{\tau s - \tau a_0}$  and rearrange terms  $\Rightarrow$

$$\tau a_1 e^{-\tau a_0} = \tau (s - a_0) e^{\tau(s - a_0)}$$



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$$W_k(\tau a_1 e^{-\tau a_0}) = W_k\left(\tau(s - a_0) e^{\tau(s - a_0)}\right) = \tau(s - a_0) \Rightarrow$$

Well known closed form:  $s = \frac{1}{\tau} W_k(\tau a_1 e^{-\tau a_0}) + a_0$

[Corless et al '96], [Shinozaki, Mori '06]





## Problem

Does the formula

$$\sigma(\Sigma) = \bigcup_{k \in \mathbb{Z}} \frac{1}{\tau} W_k(\tau a_1 e^{-\tau a_0}) + a_0$$

hold for systems with  $n > 1$ ?

We have shown in [J.,Damm '07]:

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- ii) Answer: **No**, for the general case.

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- ii) Answer: **No**, for the general case. Other literature [Asl, Ulsoy '03], with citation count 12, is not valid in the stated generality.

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# The Lambert W formula

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## Theorem ([J., Damm '07])

If  $A_0$  and  $A_1$  are simultaneously triangularizable, then

$$\sigma(\Sigma) = \bigcup_{k \in \mathbb{Z}} \sigma \left( \frac{1}{\tau} W_k(A_1 \tau e^{-A_0 \tau}) + A_0 \right).$$

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## Corollary

If  $A_0 A_1 = A_1 A_0$ , then

$$\sigma(\Sigma) = \bigcup_{k \in \mathbb{Z}} \sigma \left( \frac{1}{\tau} W_k(A_1 \tau e^{-A_0 \tau}) + A_0 \right) .$$

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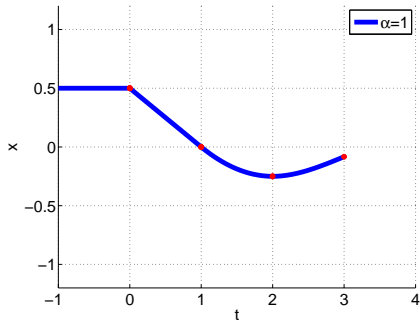
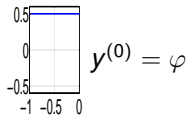
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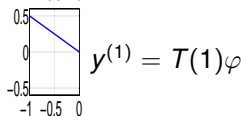
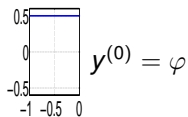
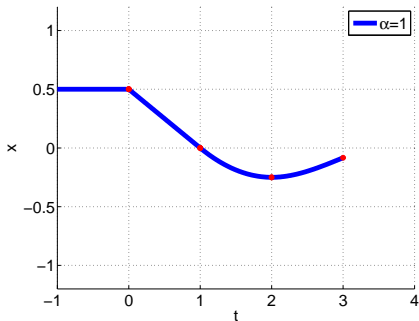
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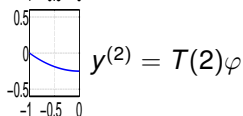
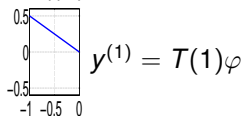
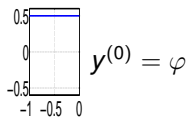
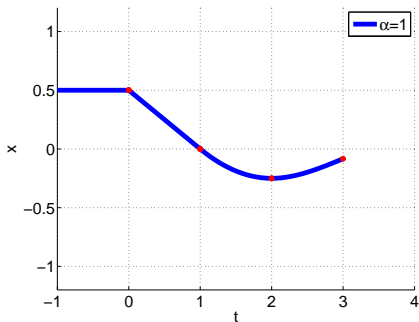
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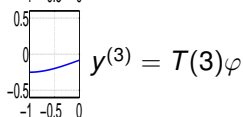
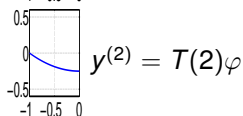
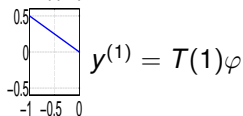
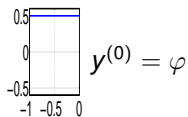
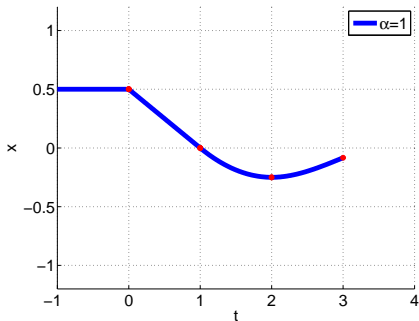
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Hot shower problem:

$$T(1)y = -\alpha \int_{-1}^t y(t) dt + y(0)$$

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More generally if  $h \leq \tau$ ,

$$(T(h)\varphi)(\theta) = \begin{cases} \psi(\theta) = \varphi(\theta - h) & \theta \leq -h \\ \text{Solution of } \dot{\psi}(\theta) = A_0\psi(\theta) + A_1\varphi(\theta + h - \tau) & \theta > -h, \end{cases}$$

Discretize with Runge-Kutta or Linear Multistep, stepsize  $h$

$$\Rightarrow S_N \in \mathbb{R}^{nN \times nN}.$$

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$$(T(h)\varphi)(\theta) = \begin{cases} \psi(\theta) = \varphi(\theta - h) & \theta \leq -h \\ \text{Solution of } \dot{\psi}(\theta) = A_0\psi(\theta) + A_1\varphi(\theta + h - \tau) & \theta > -h, \end{cases}$$

Discretize with Runge-Kutta or Linear Multistep, stepsize  $h$

$\Rightarrow S_N \in \mathbb{R}^{nN \times nN}$ .

$\Rightarrow$  If  $s \in \frac{1}{h} \ln(\sigma(S_N))$  and discretization sufficiently fine

then  $s \approx z$  for some  $z \in \sigma(\Sigma)$

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LMS, DDE-BIFTOOL [Engelborghs, Roose '99, '02], RK [Breda '05]

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# SOD(LMS) is a Padé approximation of the logarithm

By change of variables:

$$\det(-sI + A_0 + A_1 e^{-\tau s}) = 0$$

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where  $\mu = e^{hs}$  and  $h = \tau/N$ .

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$$\frac{\alpha(\mu)}{\beta(\mu)} = \frac{\mu^2 - 1}{\frac{1}{3}\mu^2 + \frac{4}{3}\mu + \frac{1}{3}}$$

$\Rightarrow$  (2) turns into *polynomial eigenvalue problem*

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Companion linearization  $\Rightarrow$  LMS(Milne-Simpson) used in  
DDE-BIFTOOL.

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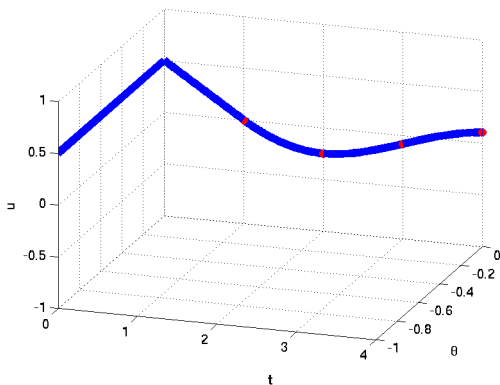
## Method 3: Infinitesimal generator discretization (IGD)

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PDE-representation: e.g. [Diekmann, van Gils '95]



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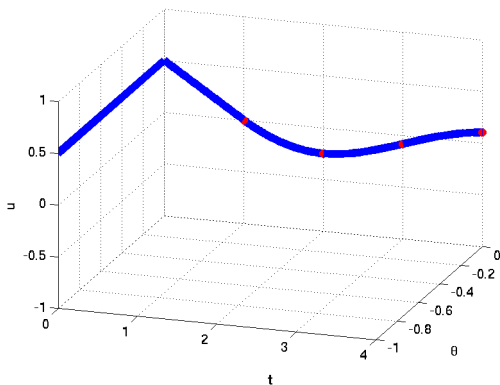
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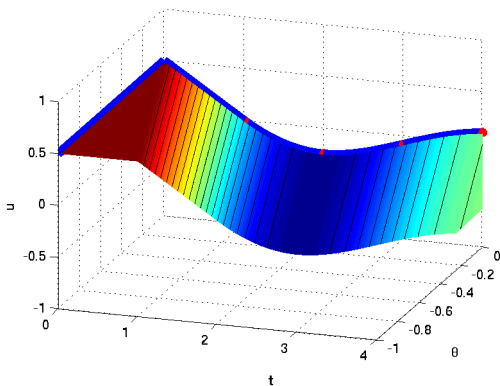
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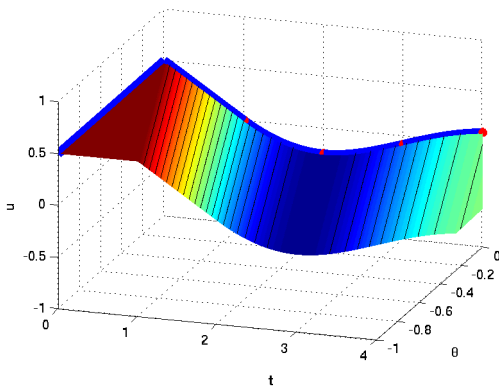
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$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial \theta}$$

$$\text{IV: } u(0, \theta) = \varphi(\theta)$$

$$\text{BC: } \frac{\partial u}{\partial t}(t, 0) = A_0 u(t, 0) + A_1 u(t, -\tau)$$

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PDE:

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{\partial u}{\partial \theta} \\ \text{IV: } u(0, \theta) = \varphi(\theta) \\ \text{BC: } \frac{\partial u}{\partial t}(t, 0) = A_0 u(t, 0) + A_1 u(t, -\tau) \end{array} \right.$$

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Semi-discretization with  
Euler [Bellen, Maset '00],

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Semi-discretization with  
Euler [Bellen, Maset '00], or  
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Alternative derivation for [Bellen, Maset '00]:  
Replace  $e^{-\tau s}$  in  $\sigma(\Sigma)$  with  $(1 + \tau s/N)^{-N}$  and  
*companion linearization*.

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## Method 4: Subspace accelerated residual inverse iteration

In the context of nonlinear eigenvalue problems (NLEVPs)

$$0 = (-sI + A_0 + A_1 e^{-\tau s})v = T(s)v.$$

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## Method 4: Subspace accelerated residual inverse iteration

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$$0 = (-sI + A_0 + A_1 e^{-\tau s})v = T(s)v.$$

### Residual inverse iteration [Neumaier '85]

Input:  $v_0 \in \mathbb{C}^n$  shift  $\mu \in \mathbb{C}$

- 1: **for**  $k = 1 \dots$  convergence **do**
- 2: Solve  $v_k^* T(s)v_k = 0$  numerically
- 3:  $v_{k+1} = v_k - T(\mu)^{-1} T(s)v_k$  and normalize
- 4: **end for**

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## Method 4: Subspace accelerated residual inverse iteration

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Idea: Expand a subspace [Voss '04] [Meerbergen '01]

### Subspace accelerated residual inverse iteration (SRI)

- 1: **for all**  $k = 1 \dots$  convergence **do**
- 2: Solve  $V^* T(s)Vy = 0$  numerically
- 3:  $v = T(\mu)^{-1} T(s)Vy$  and orthogonalize
- 4:  $V = [V, v/\|v\|]$
- 5: **end for**

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- 1: Factorize  $LU = PT(\sigma)Q$
- 2: Compute initial vectors  $V$
- 3: **for**  $m = 1 \dots m_{max}$  **do**
- 4:   **while**  $relres > RESTOL$  **do**
- 5:     Update  $Aproj$  such that  $Aproj(k) = V^* A_k V$  for all  $k$ .
- 6:     Solve projected nonlinear eigenvalue problem

$$[\mu, y, \mu_{next}, y_{next}] = \text{projectedsolve}(V, Aproj, \mu, \sigma, \sigma_t, V_l, \mu_l)$$

where  $(\mu, y)$  is the “best solution candidate”.

- 7:     Compute  $v = T(\sigma)^{-1} T(\mu) V y$  with factorization of  $T(\sigma)$ .
- 8:     Orthogonalize  $v$  against  $V$
- 9:     Expand search space  $V = [V, v/\|v\|]$
- 10:    **end while**
- 11:    Store locked values  $V_l = [V_l, v]$ ,  $\mu_l = [\mu_l, \mu]$ .
- 12:    If dimension  $V > \text{RESTARTDIMENSION}$  restart:

$$[V, \mu] = \text{restart}(V, V_l, \mu, y, \mu_{next}, y_{next})$$

- 13: **end for**



## Example 1

A PDE with delay,

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + a_0(x)u + a_1(x)u(x, t - \tau), \\ u(0, t) = u(\pi, t) = 0, t \geq 0 \end{cases} \quad (3)$$

where  $a_0(x) = a_0 + \alpha_0 \sin(x)$ ,  
 $a_1(x) = a_1 + \alpha_1 x(1 - e^{x-\pi}) + \alpha_2 x(\pi - x)$ .



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Central difference and uniform stepsize  $\Rightarrow$

$$\dot{v}(t) = \frac{(n+1)^2}{\pi^2} \begin{pmatrix} -2 & 1 & & \\ & \ddots & & \\ 1 & & 1 & \\ & & & -2 \end{pmatrix} v(t) + \begin{pmatrix} a_0(x_1) & 0 & & \\ & \ddots & & 0 \\ 0 & & 0 & \\ & & & a_0(x_n) \end{pmatrix} v(t) + \begin{pmatrix} a_1(x_1) & 0 & & \\ & \ddots & & 0 \\ 0 & & 0 & \\ & & & a_1(x_n) \end{pmatrix} v(t-\tau)$$



# Example 1: CPU consumption



Method	$n = 100$		$n = 10^3$		$n = 10^4$		$n = 10^6$	
	nof. eigs	CPU	nof. eigs	CPU	nof. eigs	CPU	nof. eigs	CPU
DDEBIFT00L 2.03 minrealpart=-20	5	18.0s	<b>MEMERR</b>					
SOD(MS, $N = 4$ )	6	0.2s	6	3.3s	<b>MEMERR</b>			
SOD(MS, $N = 8$ )	10	0.4s	9	6.1s	<b>MEMERR</b>			
IGD(PS, $N = 5$ )	5	0.3s	5	2.6s	<b>MEMERR</b>			
IGD(PS, $N = 10$ )	12	0.4s	12	27.4s	<b>MEMERR</b>			
IGD(Euler, $N = 10$ )	4	0.1s	4	1.2s	<b>MEMERR</b>			
IGD(Euler, $N = 100$ )	5	0.9s	5	12.9s	<b>MEMERR</b>			
SRI(RI) restart=0	12	1.3s	12	0.5s	12	2.8s	12	361.7s
SRI(RI) restart=20	12	0.3s	12	0.3s	12	1.9s	12	306.5s
SRI(RI) restart= $\infty$	12	0.2s	12	0.3s	12	1.9s	12	<b>292.5s</b>

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## Example 1: CPU consumption



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In the literature: Large scale DDE:  $n = 131$  [Verheyden, Green, Roose, '04].

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## Example 2

$$\begin{aligned}\dot{x}(t) &= A_0 x(t) + A_1 x(t-1), \quad t > 0 \\ x(t) &= \varphi(t), \quad t \in [-1, 0]\end{aligned}$$

Random matrices:

```
rand('seed', 0);
```

```
A0=alpha*sprandn(n, n, beta);
```

```
A1=alpha*sprandn(n, n, beta);
```



## Example 2



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Method	$n = 100$ $\alpha = 0.7$ $\beta = 0.1$		$n = 1000$ $\alpha = 6$ $\beta = 0.1$		$n = 2000$ $\alpha = 9$ $\beta = 0.1$		$n = 4000$ $\alpha = 10$ $\beta = 0.05$		$n = 10000$ $\alpha = 15$ $\beta = 0.001$	
	Accuracy	CPU	Accuracy	CPU	Accuracy	CPU	Accuracy	CPU	Accuracy	CPU
SOD(MS, $N = 2$ )	4.8e-05	0.3s	8.4e-06	19.3s	8.5e-06	109.7s	<b>MEMERR</b>			
SOD(MS, $N = 4$ )	6.1e-07	0.3s	1.0e-07	38.5s	1.0e-07	193.2s	<b>MEMERR</b>			
IGD(PS, $N = 3$ )	6.3e-03	0.3s	5.5e-03	9.8s	7.7e-03	47.8s	4.9e-03	321.5s	<b>MEMERR</b>	
IGD(PS, $N = 5$ )	2.8e-06	<b>0.1s</b>	2.3e-06	11.7s	3.7e-06	105.4s	<b>MEMERR</b>			
IGD(Euler, $N = 10$ )	1.0e-02	0.6s	1.1e-02	131.1s	1.2e-02	399.0s	<b>MEMERR</b>			
IGD(Euler, $N = 100$ )	1.0e-03	5.4s	1.1e-03	680.8s	<b>MEMERR</b>					
SRI(IGD) restart=0	3.8e-04	14.0s	2.6e-05	55.3s	1.0e-04	69.3s	1.1e-04	225.0s	1.1e-03	523.0s
SRI(IGD) restart=50	3.8e-04	29.9s	4.5e-05	91.2s	1.1e-04	75.3s	4.6e-05	245.5s	2.0e-04	521.4s
SRI(IGD) restart= $\infty$	3.8e-04	38.1s	4.5e-05	113.5s	1.1e-04	91.0s	2.3e-01	286.3s	2.0e-04	<b>518.7s</b>



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**Thanks for your attention!**

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